Elmergib University - Faculty of Art & Science KasrKhiar
Journal of Humanitarian, Scientific and Social Sciences
5th Issue June 2018

جـــامعة المرقب - كلية الآداب والعلوم قصر الأخيار
مجلة العلوم الإنسانية والعلمية والاجتماعية
العدد الخامس يونيو 2018

Improving Cache Hit Rate Using The Control Flow Graph

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Abstract

This paper provides a technique for designing a cache control unit that speeds up program execution time. This feature is highly required for modern computers to enhance system performance and efficiency. The technique focuses on solving the problem of cache misses by utilizing the control flow graph of the program behavior during its loading from the main memory and executing from the cache by the processor.The proposed cache control unit performs its task in two stages that work in parallel. These stages are implemented by the following circuits:

1- Loader circuit that loads program blocks from main memory into cache lines.
2- Replacement circuit that manages the cache lines by placing the coming program blocks into the proper cache lines and performing the replacement without misses.

This solution required that a program has to be logically partitioned according to its control flow graph into basic blocks with one exit point. This results in variable-sized program blocks to be loaded into the cache. There by in the cache there exists a block with its two successors blocks. The selection of next block to be executed from these two successors depends on the condition of the exit point of the parent block (taken or not taken branch). Thus always the next block to be executed is available in the cache. The design of the loader circuit and the replacement circuit are given in details and their functionalities are simulated. Program partitioning and the relations between program blocks are assumed to be collected from other job in a form of profile data. This data is used by the proposed circuit to control its operations and synchronizing its functions.

I. INTRODUCTION

Computers nowadays play an important role in our everyday life. Many factor increases the people to depend in computer. One of these factors is its performance represented by the speed of programs execution. Many technique where developed and are still used to enhance computer performance. One of these techniques is the use of cache memory of small capacity and less access time. This introduced many techniques and methodology to map program block between the main memory and the cache memory and which blocks should be available in cache for the processor to execute next. All that solutions utilize which so called locality principles.[1][2]

As it is known any program has many execution paths. The program blocks and the execution paths are modeled by what is so called ***Control Flow Graph CFG***. Nodes of the graph represent the program blocks and the edges represent the execution paths [5].The solution of the above mentioned problem is based on portioning the program into blocks of fixed number of exit points. In this paper the implementation of the hardware circuit of cache memory management unit is introduced and simulated.

II. CFG Example

Consider the following of code:

Program

```
x = z-2 ;
y = 2*z;
if (c) {
x = x+1;
y = y+1;
}
else {
x = x-1;
y = y-1;
}
z = x+y;
```

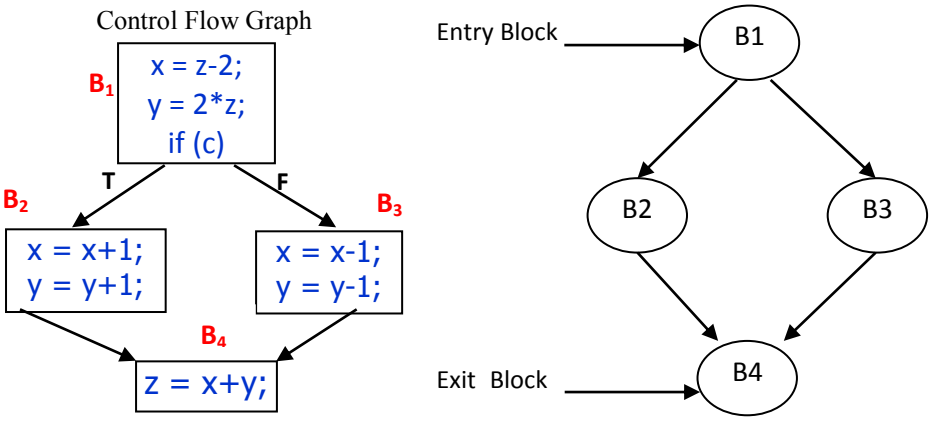


Figure (1) Control Flow Graph Example

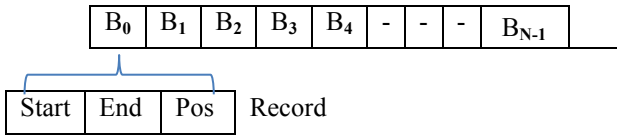
In this example, we have 4 basic blocks in particular, in this case, B1 is the **"entry block ",** B4 the **" exit block ".**A graph for this fragment has edges from B1 to B2, B1 to B3, B2 to B4, and B3 to B4 as shown in figure (1).

Possible execution =path in the graph

Possible Execution 1:
– c is true
– Program executes
- basic blocks B1, B2, B4

Possible Execution 2:
– c is false
– Program executes
- basic blocks B1, B3, B4

A. CFG Profile Representation



Start: starting address in maim memory.
End: end address in maim memory.
Pos: index in CFG data structure of the next block if jump is taken, if jump is not taken then follow next record.

B. CFG Organization

CFG organization conceptually a binary tree and physical as a graph.

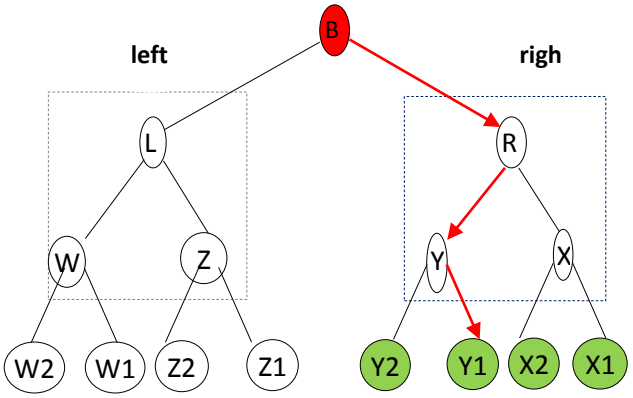


Figure (2) CFG A Binary Tree

The tree is chosen to represent the control flow graph since each basic block has at most two successors; one is entered by a control transfer instruction and the other one is the continuation block (next adjacent block followed in the main memory).[5]

D. Cache Organization

Blocks are staff in the cache start root, level one right, left and level two right , left , etc.., of the binary tree from 7 nodes tree.

Buffer address	Physical address	data	
000	0	B0	root
001	1	R0	Level one
010	2	L0	
011	3	X	Level two
100	4	Z	
101	5	Y	
110	6	W	

Figure (3) CFG Cache Organization

At first load = saturation
Next only 4 blocks are loaded, 2 for each sub tree. Staff here from the right left and last one position B0

III. Functional Units

The general block diagram is illustrated in Figure (6) below

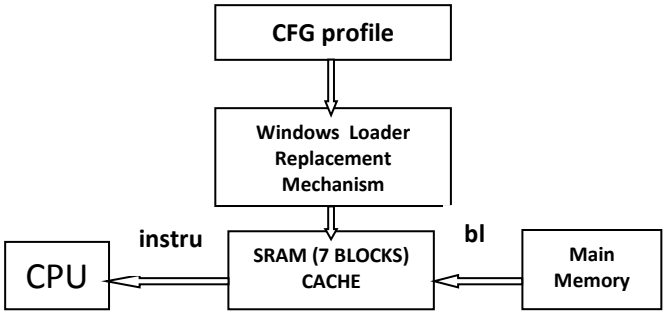


Figure (4) General Block Diagram for CFG Cache Organization

This block diagram shows idea for replacement and loader blocks from main memory to the cache memory. Execution program is divided into blocks, CFG profile contains these address blocks. At first start program execution, CPU loads these blocks in main memory, loader mechanism loads address for the needed four blocks (right or left sub tree) to main memory, main memory loads these block to the cache memory in free location, and at the same time the replacement mechanism provides free location in the cache. All needed execution blocks are ready in cache memory previously by loader mechanism.

III. Load Mechanism

This circuit used to load mechanism is illustrated in figure (5) below, this part is used to load address blocks from CFG profile to main memory.

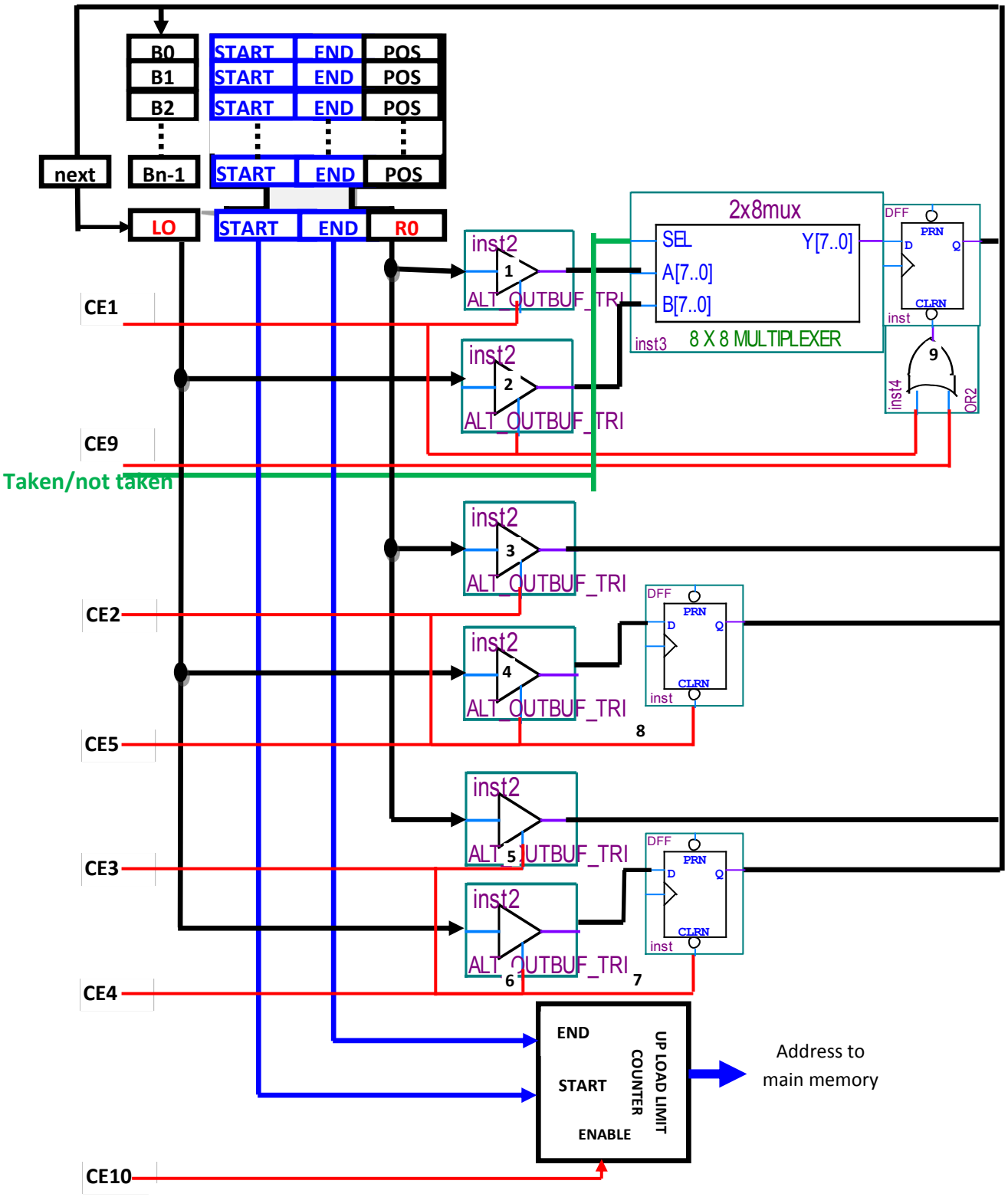


Figure (5) The Loader Mechanism Circuit

IV. Loader Circuit Operation

When the program start execution , CPU load blocks for program from CFG to main memory and load address for these block in CFG profile.

The load circuit operate is illustrated in flow chart in figure (6) below.

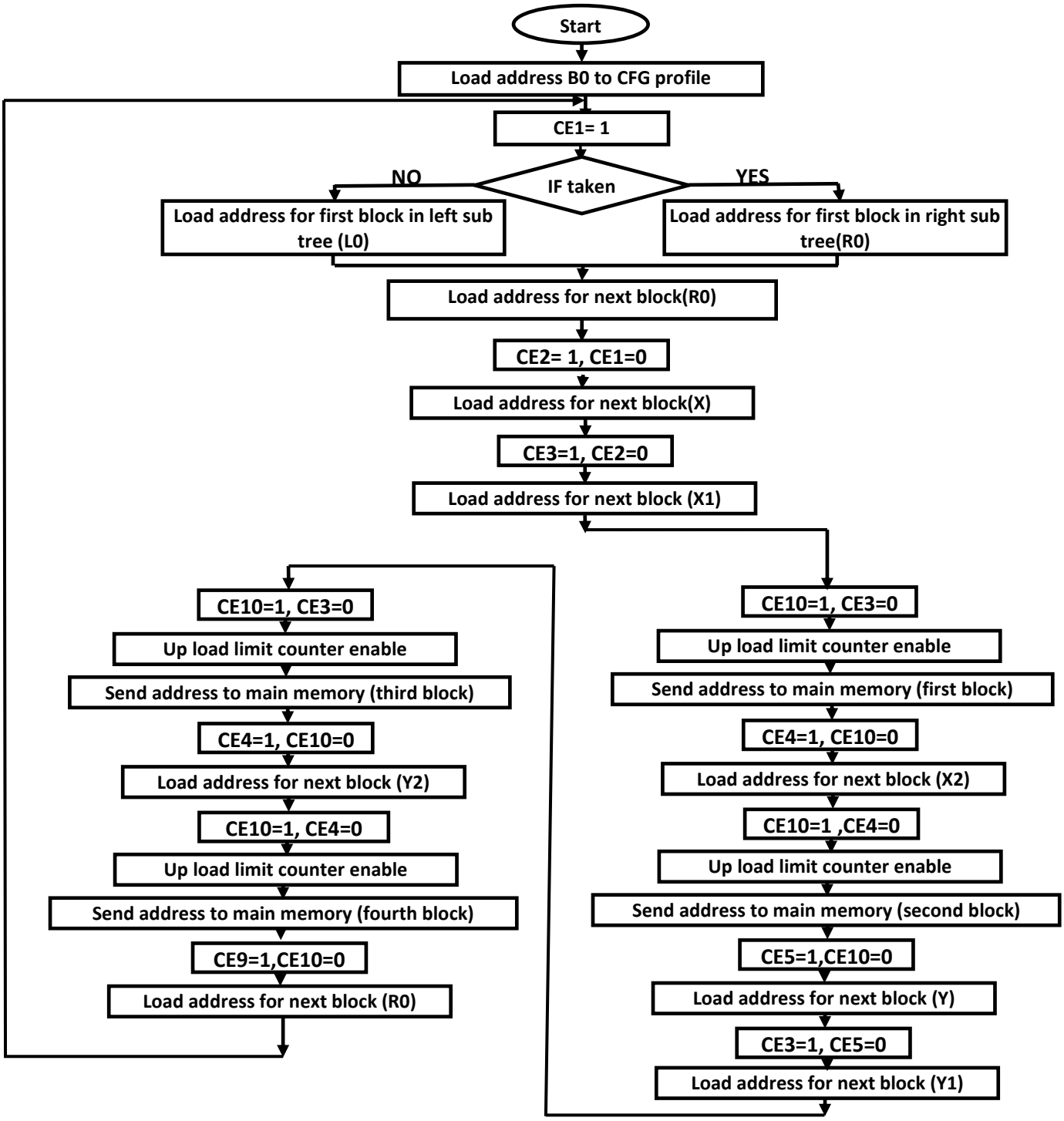


Figure (6) Flow Chart For Load Circuit

V. Replacement Mechanism

This circuit used in replacement mechanism is illustrated in figure (7) below.

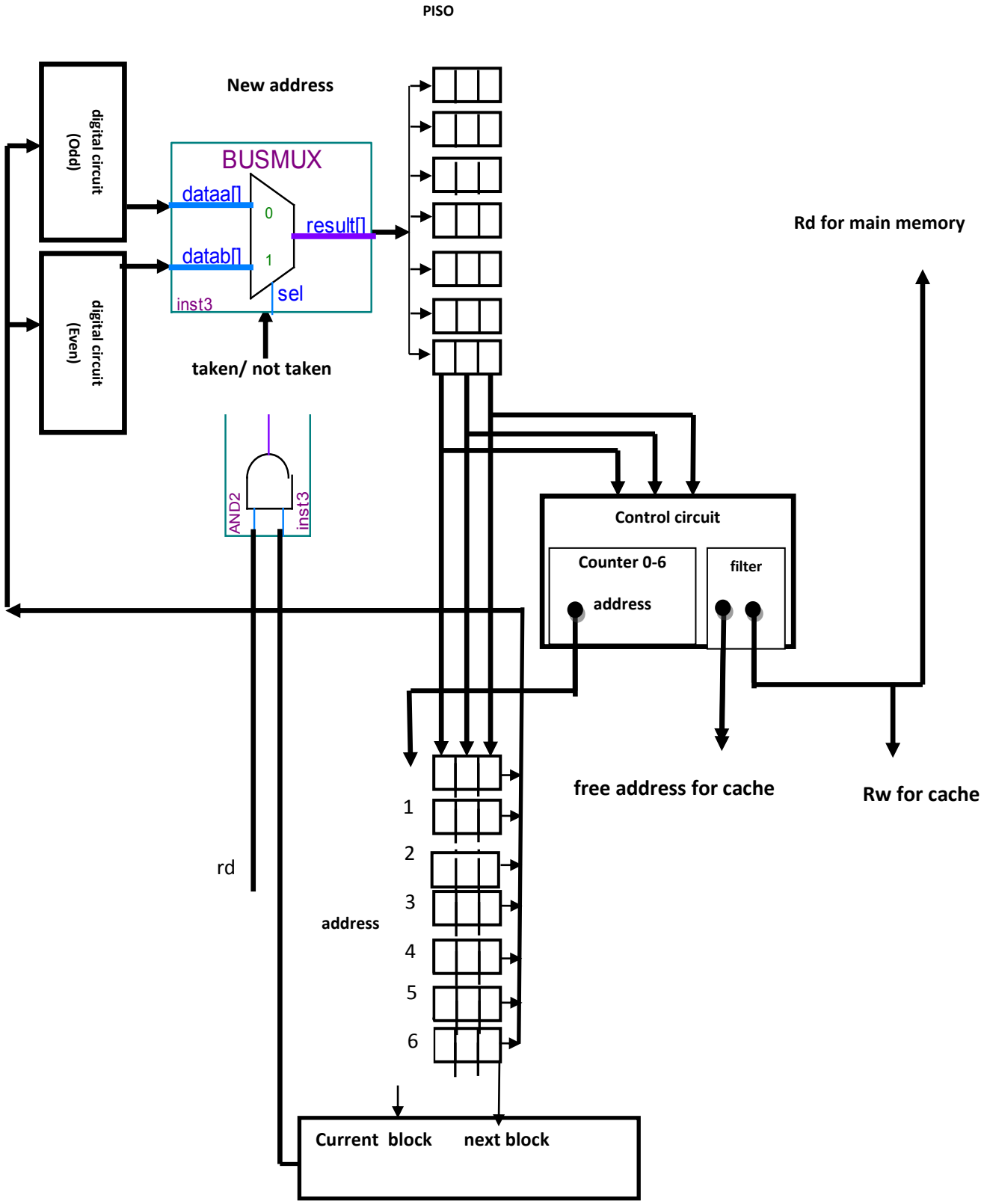


Figure (7) The Replacement Mechanism Circuit

VI. Replacement Circuit Operation

The main idea for the operation replacement circuit is shown in figure (7). It converts addresses **1,3,5 to 0,1,2** and saves its contents, because it can be used in the future, and **addresses 0,2,4,6 are converted to 3,5,4,6** and considered free position. We reload it by new data from main memory if the control signal is taken. If the control signal is not taken, the proposed replacement circuit converts **addresses 2,4,6 to 0,1,2** and saves its content because it can be used in the future. And the **addresses 0,1,3,5 convert to 3,5,4,6** and considered free position. We reload it by new data from main memory. The replacement circuit operate is illustrated in flow chart in figure (8) below

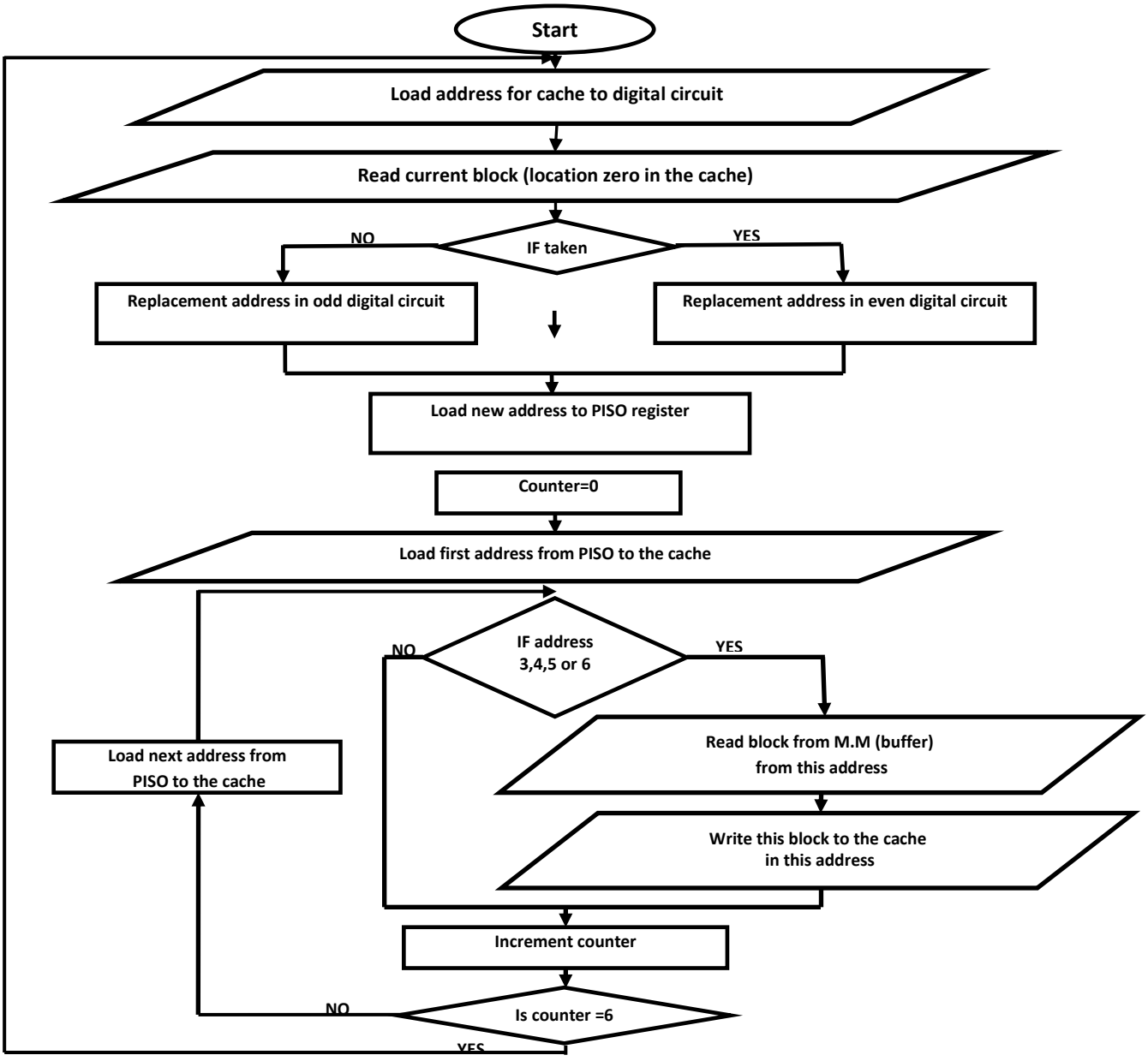


Figure (8) Flow Chart for Replacement Circuit

Results and Discussion

In figure (9), **path of execution in red color (path 1)**, current block transfers from B0 to R0, which means the branch is taken and the window is shifted to right on the tree and odd logic circuit converts addresses 0,1,2,3,4,5,6 to 3,0,5,1,4,2,6 and blocks B0,L0,Z,W are replaced with new loaded blocks X1,X2,Y1,Y2. In the next step, current block transfers from R0 to Y, the branch is not taken and the window is shifted to left on the tree and even logic circuit converts addresses 3,0,5,1,4,2,6 to 4,3,6,5,1,0,2 and blocks R0,X,X1,X2 are replaced with new loaded blocks Y3,Y4,Y5,Y6. In the next step, current block transfers from Y to Y1, the branch is taken and the window is shifted to right on the tree and odd logic circuit converts addresses 4,3,6,5,1,0,2 to 4,1,6,2,0,3,5 and blocks Y,Y2,Y5,Y6 are replaced with new loaded blocks Y7,Y8,Y9,Y10. In the following, current block transfers from Y1 to Y4, the branch is not taken and the window is shifted to left on the tree and even logic circuit converts addresses 4,1,6,2,0,3,5 to 1,5,2,0,3,4,6 and blocks Y1,Y3,Y7,Y8 are replaced with new loaded blocks Y19,Y20,Y21,Y22 And etc…

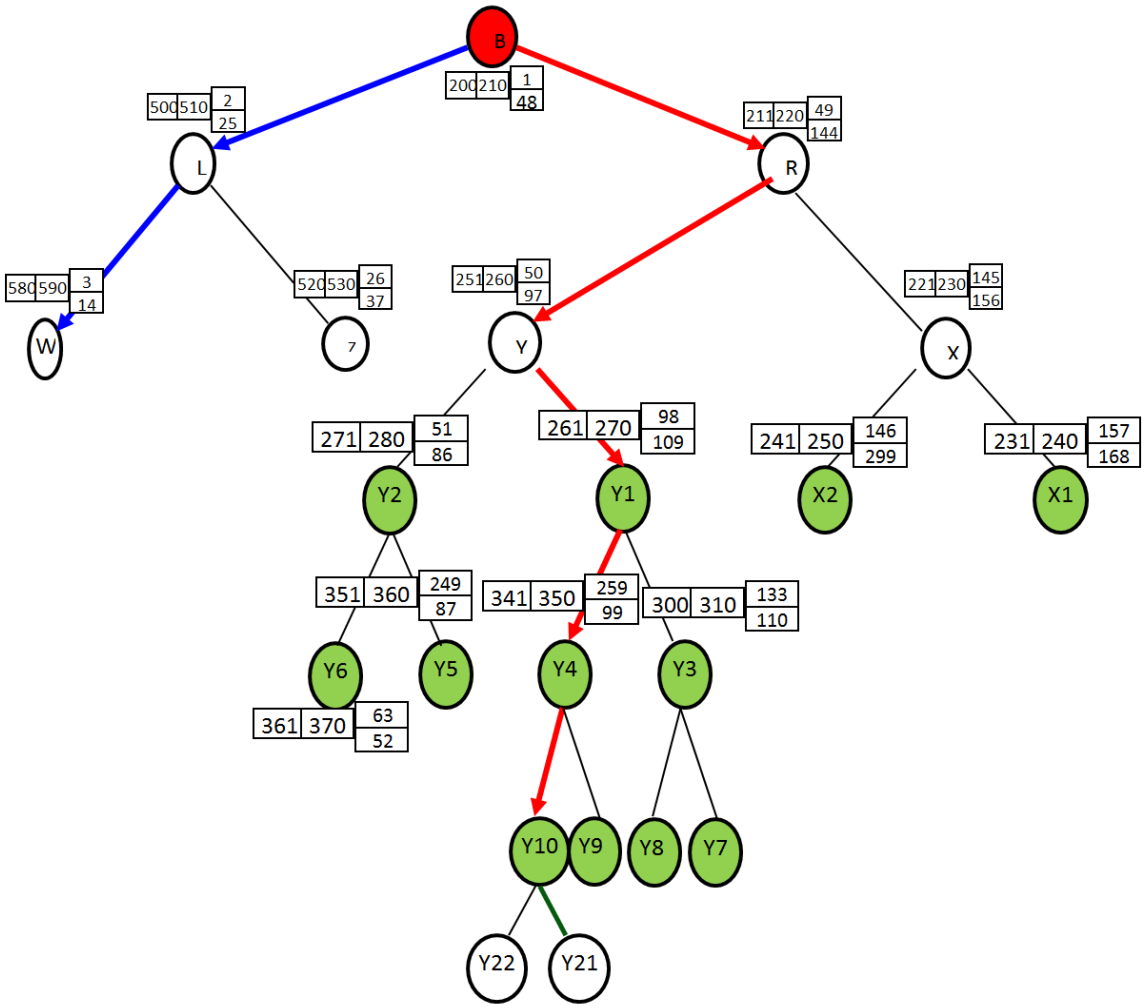


Figure (9) Binary Tree Represents The Control Flow Graph

Table (1) CFG profile information

Block Address	Block Name	Start	End	Jump NEXT	Block Address	Block Name	Start	End	Jump NEXT	Block Address	Block Name	Start	End	Jump NEXT
0	B0	200	210	48	65	Y30	…	…	…	158	X10	…	…	…
				1					66					159
1	L0	500	510	25										
				2	75	Y19	…	…	239	168	X3	…	…	319
2	W	580	590	14					76					169
				3	76	Y28	…	…	…	169	X8	…	…	…
3	W2	610	620	179					77					170
				4										
4	W6	690	700	…	86	Y5	351	360	249	179	W5	670	680	…
				5					87					180
					87	Y12	411	420	…					
14	W1	590	600	189					88	189	W3	630	640	280
				15										190
15	W4	650	660	290	97	Y1	261	270	109	190	W8	730	740	…
				16					98					191
16	W10	770	780	…	98	Y4	341	350	259					
				17					99	199	Z5	…	…	…
					99	Y10	860	870	310					200
25	Z	520	530	37					100					
				26						209	Z3	…	…	…
26	Z2	560	570	199	109	Y3	300	310	133					210
				27					110					
27	Z6	…	…	…	110	Y8	820	830	122	219	Y21	…	…	…
				28					111					220
					111	Y18	…	…	269					

The result obtained from execution program for the replacement circuit by ModelSim-Altera 6.1g (Quartus II 7.2), is illustrated in figure (10) below.

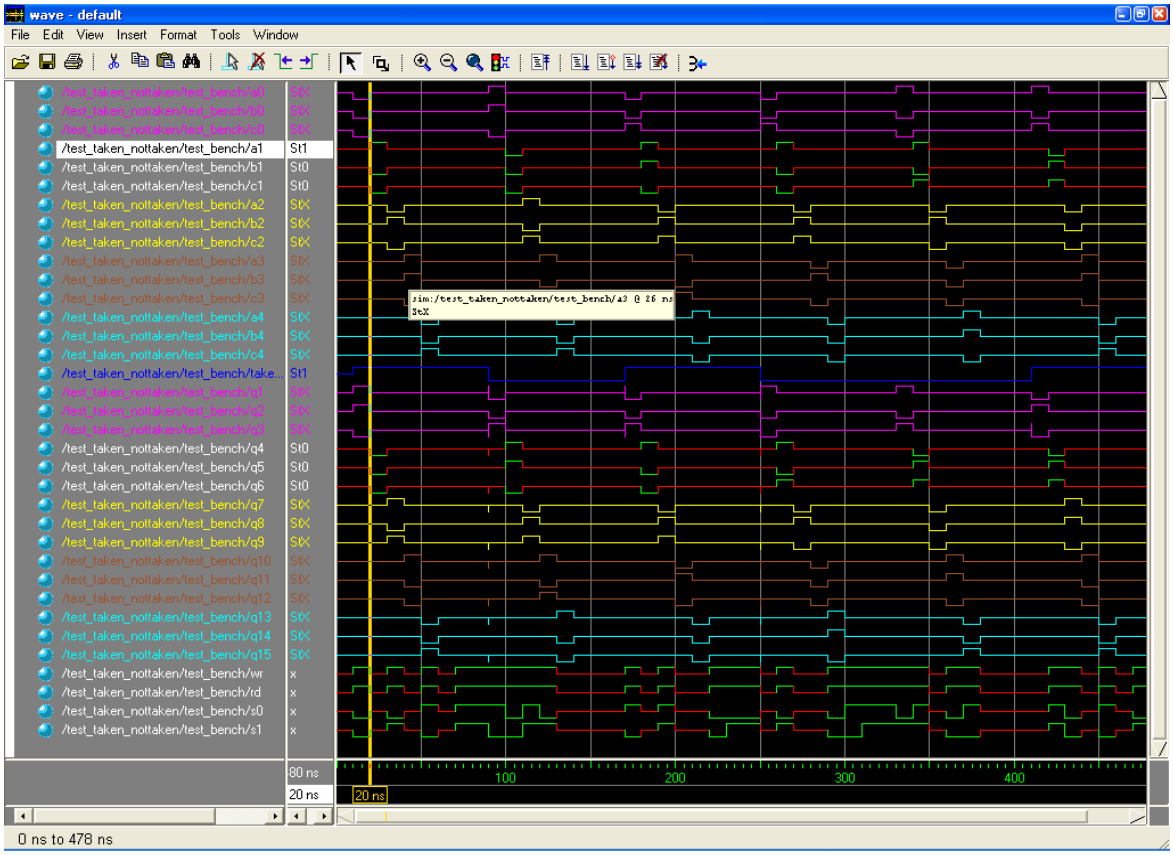
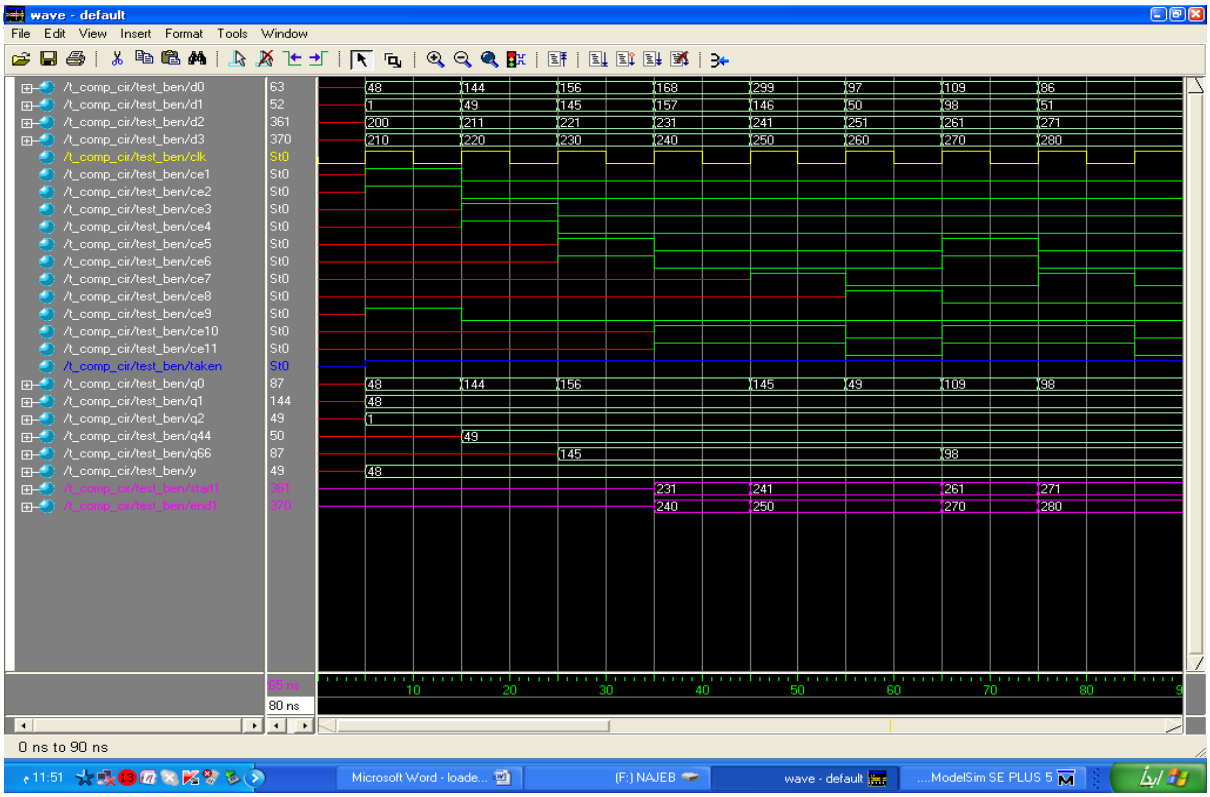


Figure (10) Simulation for Replacement Circuit



The result obtained from execution program for the loader circuit by ModelSim-Altera 6.1g (Quartus II 7.2), is illustrated in figure (11 a,b) below.

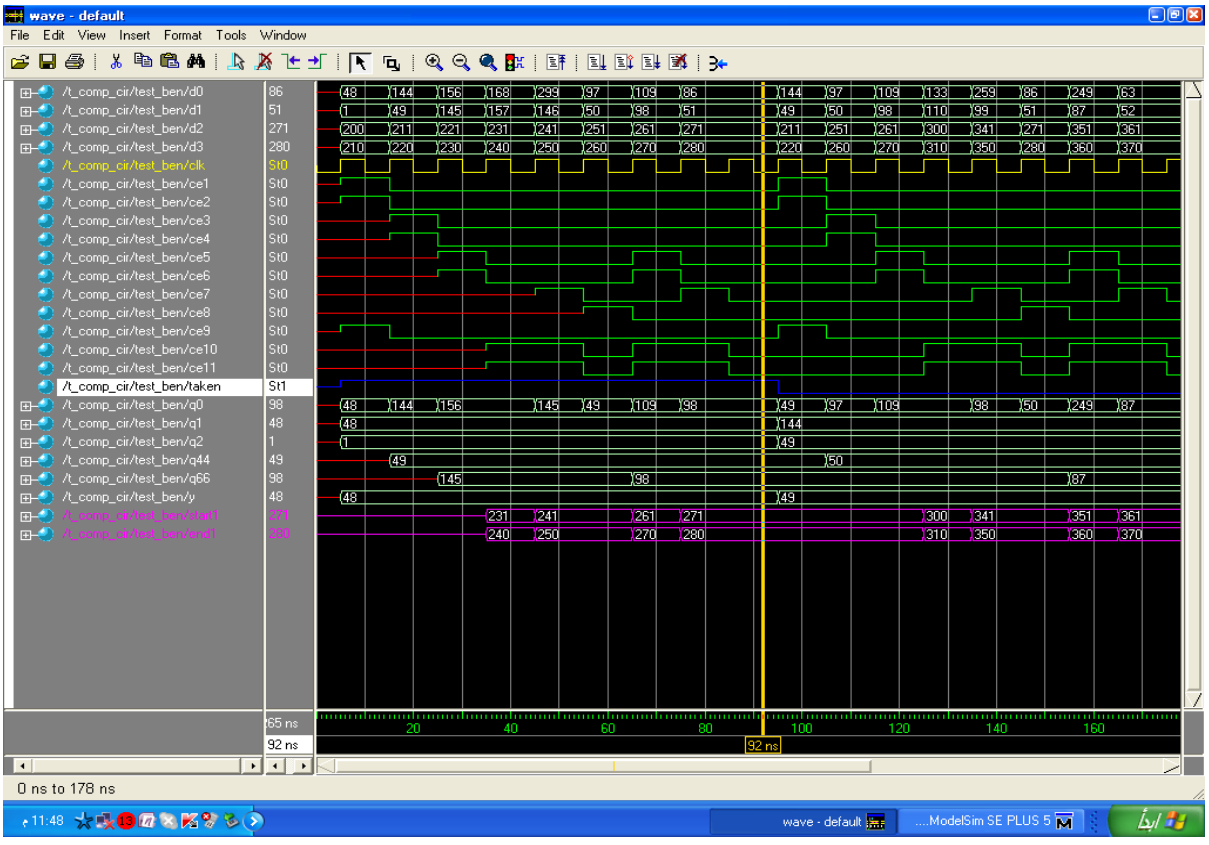
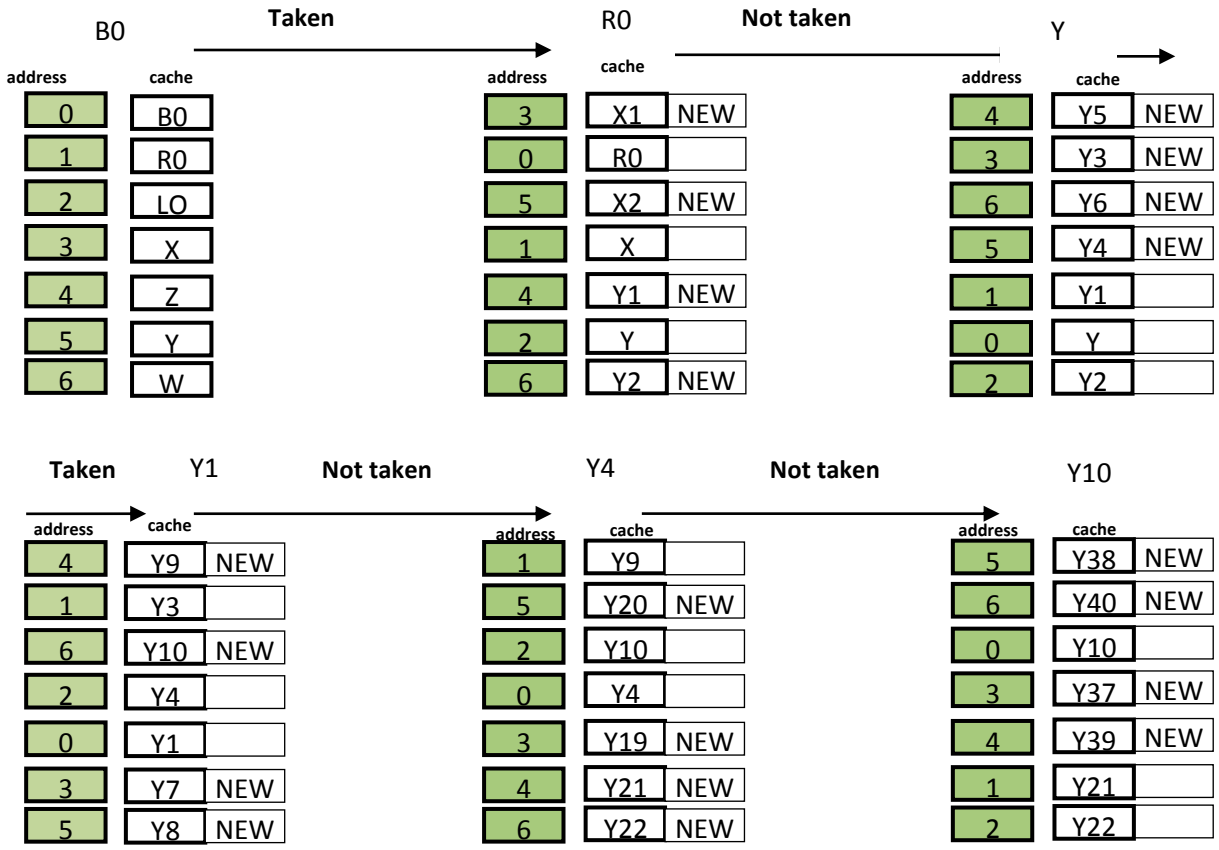


Figure (11 a ,b) Simulation for Loader Circuit

The table below (2) shows new address for cache memory after transferring current block from B0 to Y10 (Path 1).

Table (2) Cache Memory Status When Execute Path1



VII. Summary of Results

After the designing odd logic circuit and even logic circuit and testing it and evaluating by ModelSim-Altera 6.1g (Quartus II 7.2), the results obtained from simulation are equal to the predicted results. These results are illustrated in table (2), and when testing the detection circuit and comparing the results obtained from simulation with the predicted results, we have the same results. These results are illustrated in figure (10). After that, we connect these circuits with each other by multiplexer and parallel input serial output (PISO) register, and testing it many times for random paths. These circuits always give the same predicted results. This circuit is connected to cache memory and main memory to get replacement circuit in figure (7). After design all parts in complete circuits, The testing, evaluating and investigating the loader circuit in figure (5) by ModelSim-Altera 6.1g (Quartus II 7.2), and when comparing between the predicted results in the table (2) with the obtained results from simulation in experment1 for loader circuit in figure (10), equal results are obtained. And when testing, evaluating and investigating the replacement circuit in figure (7) by ModelSim-Altera 6.1g (Quartus II 7.2), and when comparing between the predicted results in table (2) with the obtained results from simulation in experment1(path1-red color) for replacement circuit in figure (10), equal results are obtained.

VIII. Conclusion

During the work on this paper the previous techniques used for cache memory mapping and replacement strategies were surveyed to highlight their functionalities, capabilities and limitations for minimizing cache misses. It was found that all those techniques work on the principles of locality: Spatial locality and temporal locality. Those two principles do not put into account the prediction of next block to be loaded into the cache and the next block to be entered and executed. This results in that each technique works good with some programs to minimize cache misses and poor with other programs. This depends on the nature and structure of the program being executed.

By utilizing the behavior of a program represented by its control flow graph, a new technique for cache memory mapping and replacement is proposed. Its corresponding digital circuit was designed and simulated. The circuit consists of two parts that work in parallel. One part performance the task of loading program blocks from the main memory into the cache lines. The other part performance the required replacement. The circuit was simulated using Verilog hardware simulation language and tested using Quartus II 7.2. The results obtained from the simulation verified the proposed idea and it was found that always there exist in the cache successor blocks organized as a binary tree. This eliminating processor wait states and hence a program is executed continuously without cache miss.

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